

**CSE 5500 Algorithms. Fall 2018**  
Homework 2 Solutions

- The coefficients of the polynomial are given by  $\binom{n}{i}$ ,  $i = 0, 1, \dots, n$ .  
Since  $\binom{n}{i} = \binom{n}{i-1} (n-i+1)/i$ , the coefficients can be computed in time  $O(n)$ .  
FFT can be used to multiply two  $n$ th degree polynomials in  $O(n \log n)$  time. We can compute the coefficients of  $(1+x)^n$  by multiplying  $(1+x)^{n/2}$  and  $(1+x)^{n/2}$ . If  $T(n)$  is the time needed to compute  $(1+x)^n$ , then,  $T(n) = T(n/2) + O(n \log n)$ , which solves to  $O(n \log n)$ .
- Let  $A$  be a *Toeplitz* matrix and  $B$  be an  $n \times 1$  vector. Let's consider the multiplication of the lower triangular part of  $A$  (including the main diagonal elements) with  $B$ .

Let the elements of  $A$  be the following:

$$a_{n,n} = a_{n-1,n-1} = a_{n-2,n-2} = \dots = a_{2,2} = a_{1,1} = a_1$$

$$a_{n,n-1} = a_{n-1,n-2} = a_{n-2,n-3} = \dots = a_{2,1} = a_2$$

$$a_{n,n-2} = a_{n-1,n-3} = a_{n-2,n-4} = \dots = a_{3,1} = a_3$$

$\vdots$

$$a_{n,1} = a_n$$

Let the elements of  $B$  be the following:

$$b_{1,1} = b_1, b_{2,1} = b_2, \dots, b_{n,1} = b_n$$

Multiplication of the lower triangular part of  $A$  with  $B$  gives the following:

$$\begin{bmatrix} a_1 b_1 \\ a_2 b_1 + a_1 b_2 \\ a_3 b_1 + a_2 b_2 + a_1 b_3 \\ \vdots \end{bmatrix}$$

We can notice that the above is nothing but the multiplication of two polynomials  $(a_1 + a_2x + a_3x^2 + \dots)$  and  $(b_1 + b_2x + b_3x^2 + \dots)$ .

Since the polynomials can be multiplied in  $O(n \log n)$  time, the matrices can also be multiplied in  $O(n \log n)$  time. Multiplication of the upper triangular elements of  $A$  with  $B$  is symmetrical to the above and it would not affect the asymptotic complexity.

- Using Taylor series expansion for  $f(\cdot)$ ,

$$f(a+x) = f(a) + xf^1(a) + \frac{x^2}{2!}f^2(a) + \dots + \frac{x^n}{n!}f^n(a)$$

where  $f^i(x)$  stands for the  $i$ th derivative of  $f(x)$ . Let  $F(x)$  denote  $f(a+x)$ . Evaluate  $F(x)$  at the  $n$ th roots of unity. This can be done in  $O(n \log^2 n)$  time as was mentioned in class (see Section 9.5 in the text – An  $n$ th degree polynomial can be evaluated at  $n$  arbitrary points in  $O(n \log^2 n)$  time). Then, use inverse FFT to compute the coefficients of  $F(x)$ . This can be done in  $O(n \log n)$  time. Once the coefficients of  $F(x)$  are known, it is easy to determine the derivatives.

$$\text{Run time} = O(n \log^2 n) + O(n \log n) + O(n) = O(n \log^2 n).$$

**Another solution:** Let  $f(x) = a_n x^n + a_{n-1} x^{n-1} + \dots + a_1 x + a_0$ . Then,  $f'(x) = n a_n x^{n-1} +$

$(n-1)a_{n-1}x^{n-2} + \dots + 2a_2x + a_1$ ;  $f''(x) = n(n-1)a_nx^{n-2} + (n-1)(n-2)a_{n-1}x^{n-3} + \dots + 2a_2$ ;  $f'''(x) = n(n-1)(n-2)a_nx^{n-3} + (n-1)(n-2)(n-3)a_{n-1}x^{n-4} + \dots + 6a_3$ ; and so on. Now consider the following two polynomials:  $A(x) = (n!a_n)x^{n-1} + ((n-1)!a_{n-1})x^{n-2} + \dots + (2!)a_2x + a_1$  and  $B(x) = \frac{a^{n-1}}{(n-1)!} + \frac{a^{n-2}}{(n-2)!}x + \dots + \frac{a^2}{2!}x^{n-3} + ax^{n-2} + x^{n-1}$ . Compute the product of  $A(x)$  and  $B(x)$  in  $O(n \log n)$  time. We can obtain the required derivatives from the coefficients of this product. The total run time is  $O(n \log n)$ . However note that the coefficients of  $A(x)$  could become very large creating practical difficulties.

4. Let  $C$  be a cycle with  $k$  vertices. Let the edge  $e$  of  $C$  with the maximum weight be a part of a minimum-cost spanning tree of  $G$ . There exists at least one edge,  $e'$ , of  $C$  which is not a part of the minimum-cost spanning tree ( $k$  vertices can be connected by  $k-1$  edges and  $C$  contains  $k$  edges). By replacing  $e$  in the spanning tree with  $e'$ , we can obtain a new spanning tree whose cost will be less than that of the original minimum-cost spanning tree. This is a contradiction and hence, the edge with the maximum weight of  $C$  can not be part of a minimum-cost spanning tree of  $G$ .

5. Let  $X = x_1, x_2, x_3, \dots, x_n$  and  $Y = y_1, y_2, y_3, \dots, y_m$ .

Let  $L(i, j)$  represent the length of the longest common subsequence between  $x_1, x_2, \dots, x_i$  and  $y_1, y_2, \dots, y_j$  such that the common subsequence ends at  $x_i$  and  $y_j$  in  $X$  and  $Y$  respectively. Assuming that  $L[i-1, j-1]$  has already been calculated, compute  $L[i, j]$  as follows:

if  $x[i] = y[j]$  then  $L[i, j] = L[i-1, j-1] + 1$

else  $L[i, j] = 0$ .

Compute  $L[i, j]$  for  $0 \leq i \leq n$ ;  $0 \leq j \leq m$ . Scan through all these values and pick the largest  $L[i, j]$ . Computing  $L[i, j]$  from  $L[i-1, j-1]$  takes constant time. Thus the total run time is  $O(nm)$ .

6. (a)  $C(i, j) = \min_{i \leq k \leq j} \{C(i, k) + C(k+1, j) + D(i-1)D(k)D(j)\}$

(b) for  $i = 1$  to  $r$  do

    for  $j = i+1$  to  $r$  do

        for  $k = i$  to  $j$  do

$C[i, j] = \min(C[i, j], C[i, k] + C[k+1, j] + D(i-1)D(k)D(j))$

7. We can verify all the properties that a flow function is required to satisfy. Let  $F = \alpha f_1 + (1-\alpha)f_2$ . Then, i) **Capacity constraint:** For all  $u, v \in V$  we have:  $F(u, v) = \alpha f_1(u, v) + (1-\alpha)f_2(u, v) \leq \alpha c(u, v) + (1-\alpha)c(u, v) \leq c(u, v)$ ; ii) **Skew symmetry:** For all  $u, v \in V$ ,  $F(u, v) = \alpha f_1(u, v) + (1-\alpha)f_2(u, v) = -\alpha f_1(v, u) - (1-\alpha)f_2(v, u) = -F(v, u)$ ; iii) **Flow conservation:** For all  $u \in V - \{s, t\}$ ,  $\sum_{v \in V} F(u, v) = \sum_{v \in V} \alpha f_1(u, v) + (1-\alpha)f_2(u, v) = \alpha \sum_{v \in V} f_1(u, v) + (1-\alpha) \sum_{v \in V} f_2(u, v) = 0$ .

8. Going through the steps of Ford-Fulkerson method we realize that the value of maximum flow is 19.